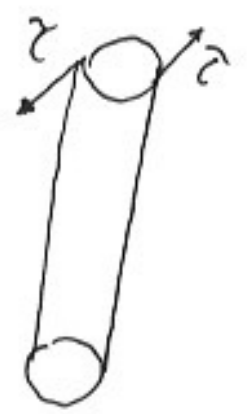


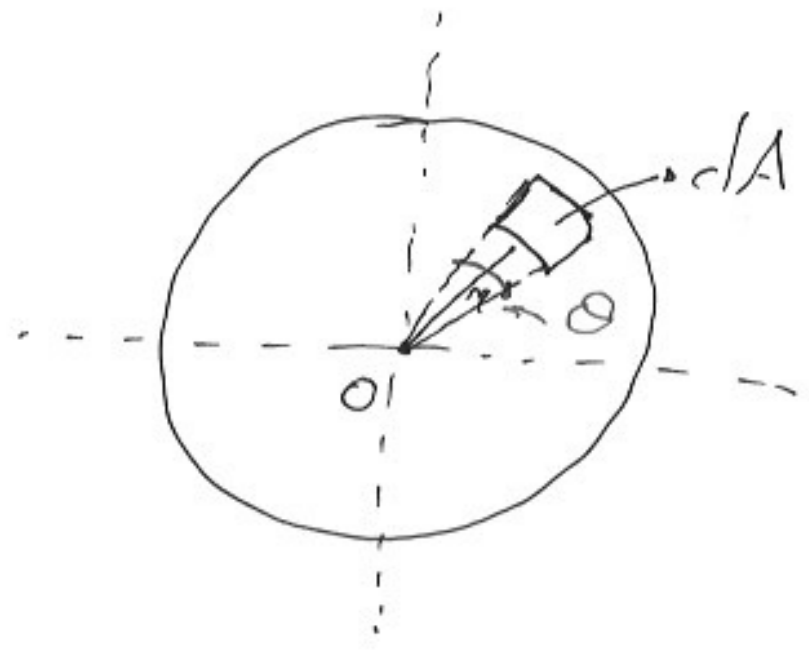
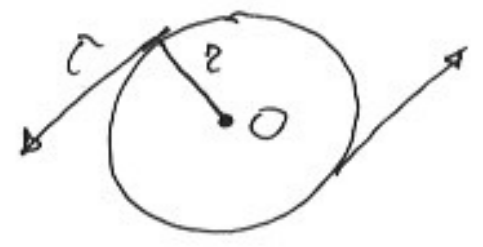
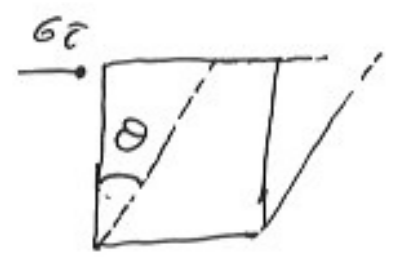
Stress normale



$$\sigma = \frac{F}{A}$$



Sforzo di taglio



$$\tau r = \sigma \cdot r$$

$$\sigma r = \frac{\tau \cdot r}{J}$$

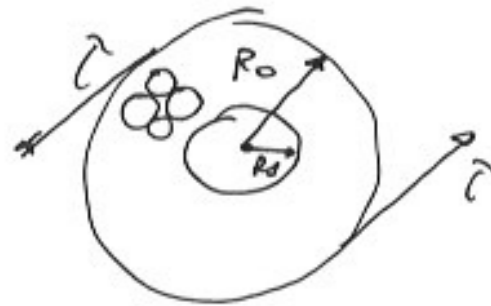
J = momento di Inerzia
Torsionale

$$J = \sum r^2 dA = \int_S r^2 dA$$

$$dA = r dr d\theta$$

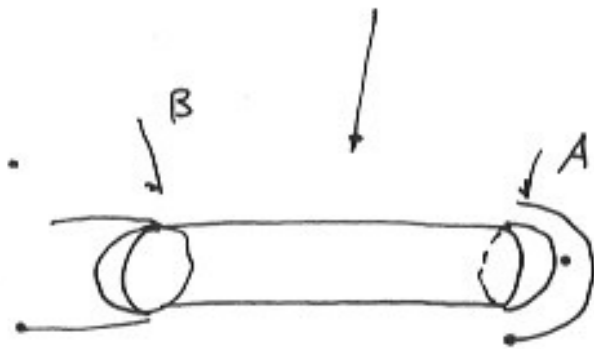
$$J = \int_S r^3 dr d\theta = \iint r^3 dr d\theta = \int_0^{2\pi} d\theta \int_0^? r^3 dr = 2\pi \frac{r^4}{4} = \pi \frac{r^2}{2} \quad (2)$$

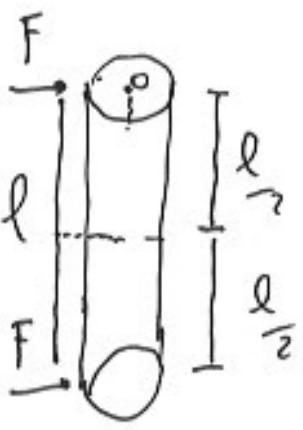
$$J = \frac{\pi}{2} (R_o^4 - R_i^4)$$



$$\sigma_r = \frac{M \cdot r}{\frac{\pi}{2} (R_o^4 - R_i^4)}$$

Forza di bending



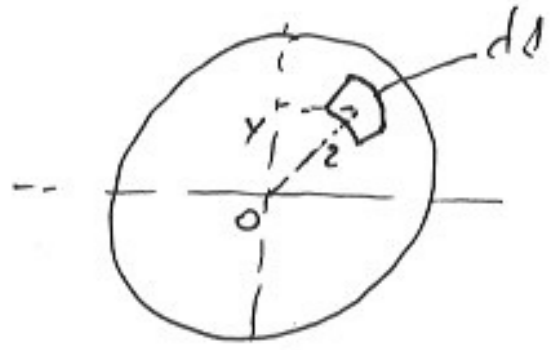


$$M_b = F \cdot \frac{l}{2}$$

$$\sigma_b = \frac{M_b \cdot r}{I}$$

$I =$ moment of inertia

$$I = \sum y^2 dA$$




$$y = r \cos \theta$$

$$y^2 = r^2 \cos^2 \theta$$

$$I = \int_S r^2 \cos^2 \theta \cdot r \, dr \, d\theta = \iint r^3 \cos^2 \theta \, dr \, d\theta = \int r^3 \, dr \int \cos^2 \theta \, d\theta$$

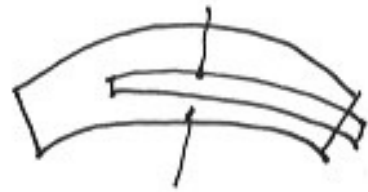
$$= \frac{r^4}{4} \int \cos^2 \theta \, d\theta \quad \cos^2 \theta = \frac{1 + \cos 2\theta}{2}$$

$$\int \cos^2 \theta d\theta = \int \frac{1 + \cos^2 \theta}{2} d\theta = \int_0^{2\pi} \frac{1}{2} d\theta + \int_0^{2\pi} \frac{\cos^2 \theta}{2} d\theta = \frac{1}{2} \cdot 2\pi = \pi \quad (4)$$

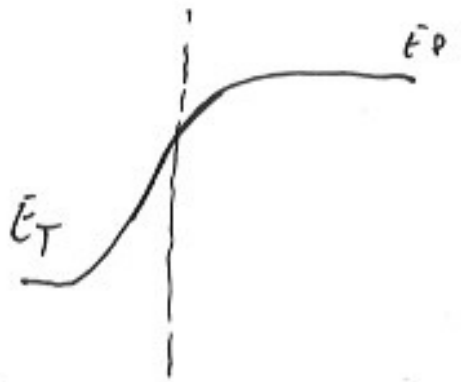
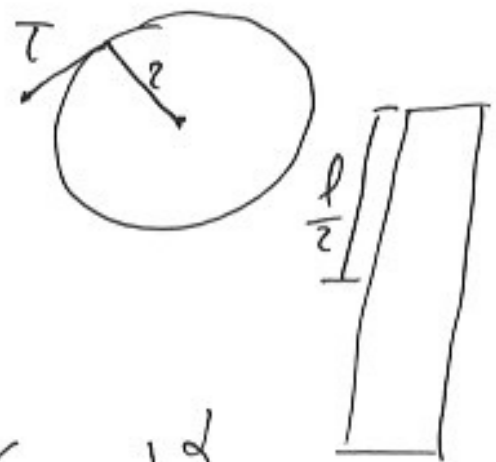
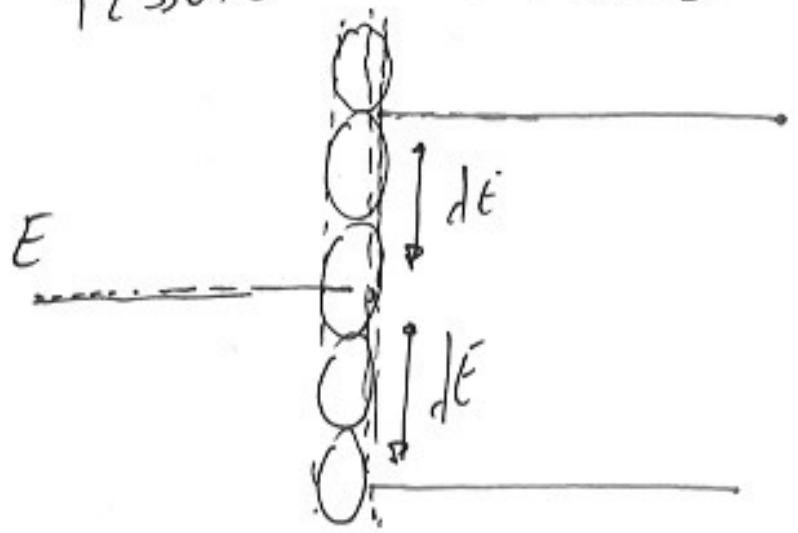
$$I = \frac{\pi}{4} z^4$$


$$I = \frac{\pi}{4} (R_o^4 - R_i^4)$$

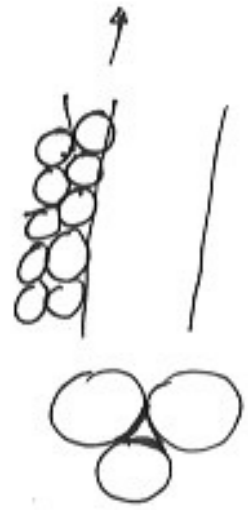
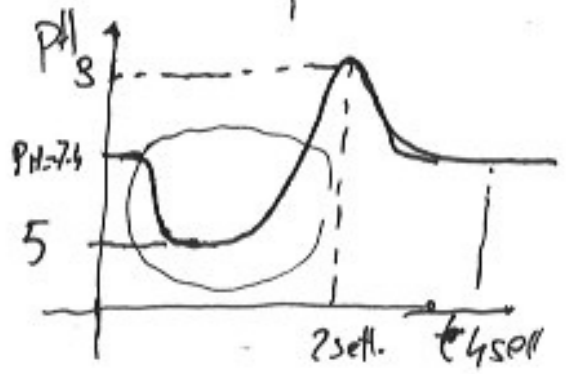
$$C_b = \frac{\pi b \cdot z}{\frac{\pi}{4} (R_o^4 - R_i^4)}$$



TESSUTO Protosi



$$E = E_0 (1 - p)^d$$

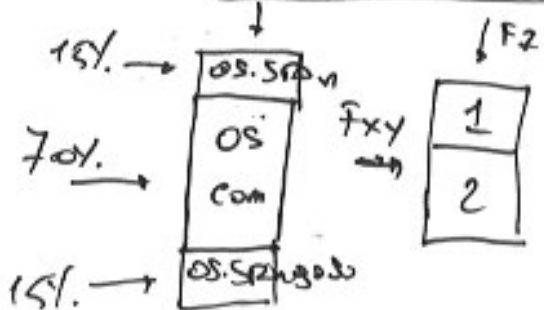


$$E_{\text{osso sano}} = E_{\text{osso residuo + protesi}}$$

$$\sigma = \epsilon E \quad \epsilon = \frac{\sigma}{E}$$

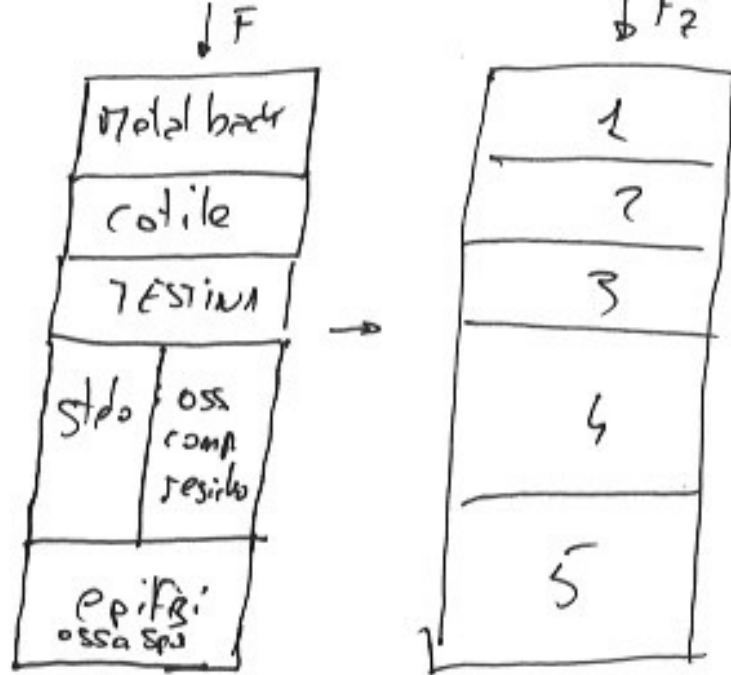
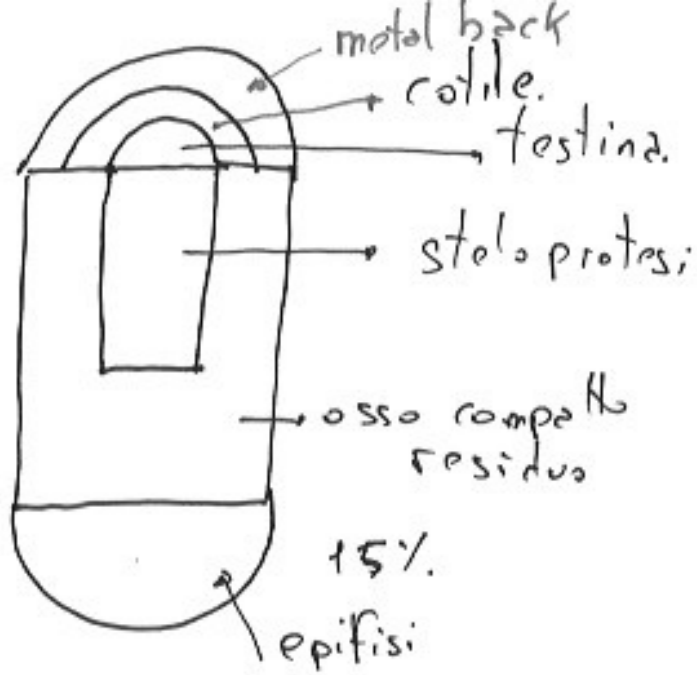
$$\frac{\sigma_{\text{osso sano}}}{E_{\text{osso sano}}} = \frac{\sigma_{\text{osso residuo + protesi}}}{E_{\text{osso residuo + protesi}}}$$

$$E_{\text{osso sano}} = E_{\text{osso residuo + protesi}}$$



$$E_{\text{oss. sano}}^z = \frac{E_{oc}^z \cdot E_{os}}{f_{os} \cdot E_{oc}^z + f_{oc} E_{os}}$$

$$E^{xy} = E_{oc} \cdot f_{oc} + E_{os} \cdot f_{os}$$



$$f_s = \frac{V_s}{V_T}$$

