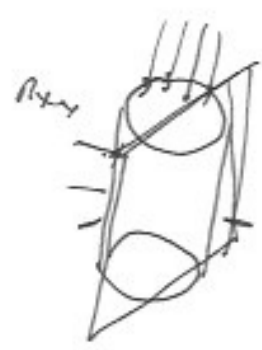


Conserviamo legamento femorale.

hst, 2st, 2int, 2est o d sp fon



$$\frac{R_z'}{\pi 2int \cdot w_{lante}} = \frac{R_{xy}}{2\pi 2ph + sp_{int} \cdot w_{lante}}$$

$$\sigma = \frac{R_z}{\pi R_c^2}$$

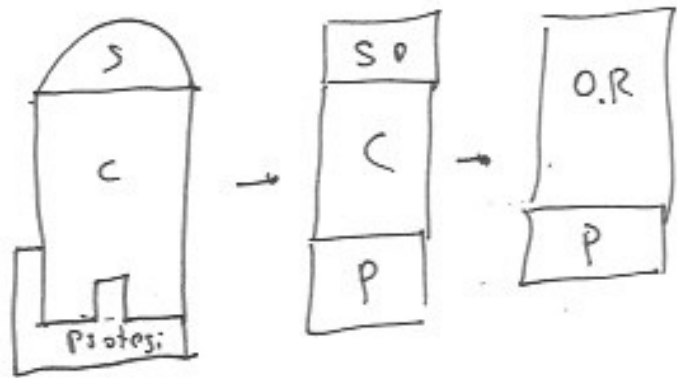
$$\sigma = \frac{R_z}{\frac{\pi R_c^2}{2}}$$

$$R_z' = \frac{R_z}{2}$$

$$R_{xy}' = \frac{R_{xy}}{2}$$

$$E_z^0 = \frac{E_c E_s}{0.3 E_s + 0.7 E_c}$$

$$E_{xy}^0 = 0.3 E_s + 0.7 E_c$$



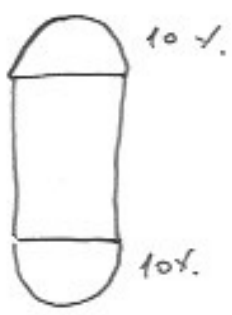
$$E_z = \frac{E_{OR}^z \bar{E}_P}{k_P E_{OR}^z + k_{OR} \bar{E}_P}$$

$$E_{xy} = k_P \bar{E}_P + k_{OR} E_{OR}^{xy}$$

$$k_P + k_{OR} = 1$$

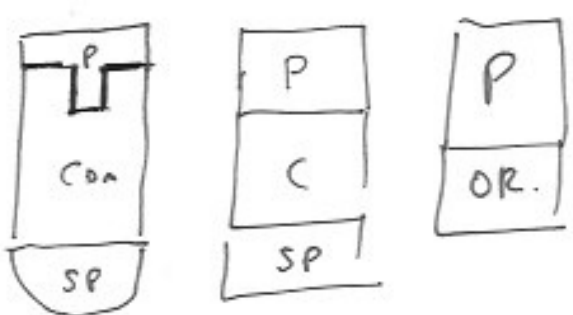
Isostress.

Tibiale



$$E_o^z = \frac{E_c^z E_s}{0.2 E_c^z + 0.8 E_s}$$

$$E_o^{xy} = 0.2 E_s + 0.8 E_c^{xy}$$



$$E^z = \frac{\bar{E}_P E_{OR}^z}{k_P E_{OR}^z + k_{OR} \bar{E}_P}$$

$$E_{xy} = k_P \bar{E}_P + k_{OR} E_{OR}^{xy}$$

$$k_P + k_{OR} = 1$$

2p, hp, 2 part, sp. tibiale

isostress



$$\frac{R'z}{\frac{\pi R^2 t b}{2}} = \frac{R'xy}{\pi z p h p + \pi R t b \cdot b t b}$$

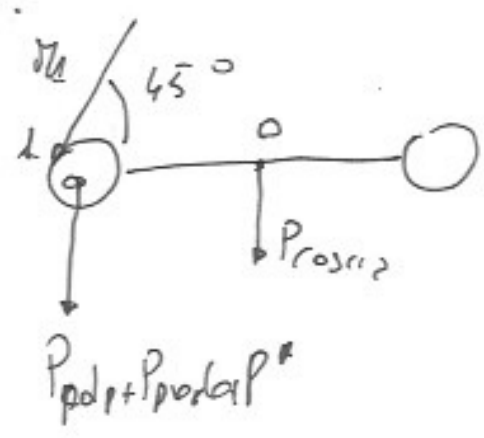
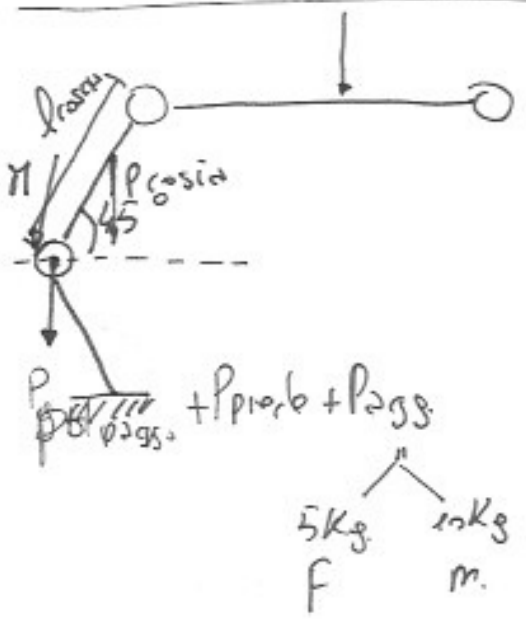
$\Pi =$  componente rotile.

$$\delta \leq 10 \mu\text{m}/\text{cm}$$

$$0.5 < \delta < 1 \text{ cm}$$

Senza conservazione del legamento

Metodo puntuale.



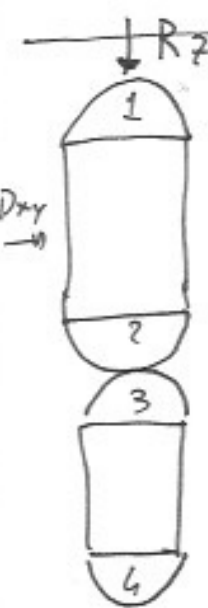
$$M_{104} = P_{cos 45} \cdot \frac{l_c}{2}$$

$$M_1 = P_{cos 45} \frac{l_c}{2 \cos A}$$

$$R_z = -P_{psl} - P_{piedo} - P_{argg} - P_{rosie} - \Pi_1 \text{ sen } \alpha \quad (4)$$

$$\alpha = 45^\circ$$

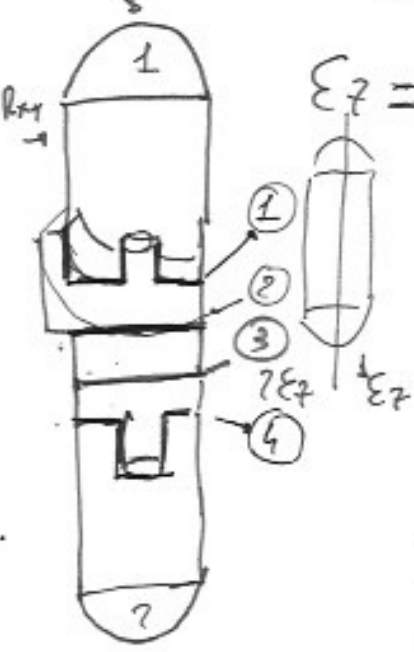
$$R_{xy} = -\Pi_1 \text{ cos } \alpha$$



$$\epsilon_z = \frac{R_z}{2\pi R_{ep1}^2} \cdot \frac{1}{E_{os}} + \frac{R_z}{\pi R_{fer}^2} \cdot \frac{1}{E_{oc}^2} + \frac{R_z}{2\pi R_{ep}^2} \cdot \frac{1}{E_{os}} + \frac{R_z}{2\pi R_{ep3}^2} \cdot \frac{1}{E_{os}} + \frac{R_z}{\pi R_{tib}^2} \cdot \frac{1}{E_{oc}^2} + \frac{R_z}{2\pi R_{ep1}^2} \cdot \frac{1}{E_{os}}$$

$$\epsilon_{xy} = \frac{R_{xy}}{\frac{2}{3} \pi R_{ep1}^3 \frac{1}{h_{ep1}}} \cdot \frac{1}{E_{os}} + \frac{R_{xy}}{2\pi R_{fer}^2 h_{fer}} \cdot \frac{1}{E_{oc}^{xy}} + \frac{R_{xy}}{\frac{2}{3} \pi R_{ep2}^3 \frac{1}{h_{ep2}}} \cdot \frac{1}{E_{os}}$$

$$\frac{1}{E_{os}} + \frac{R_{xy}}{\frac{2}{3} \pi R_{ep3}^3 \frac{1}{h_{ep3}}} \cdot \frac{1}{E_{os}} + \frac{R_{xy}}{2\pi R_{tib}^2 h_{tib}} \cdot \frac{1}{E_{oc}^{xy}} + \frac{R_{xy}}{\frac{2}{3} \pi R_{ep1}^3 \frac{1}{h_{ep1}}} \cdot \frac{1}{E_{os}}$$



$$\epsilon_z = \frac{R_z}{\pi R_{ep1}^2} \cdot \frac{1}{E_{os1}} + \frac{R_z}{\frac{\pi R_{fer}^2}{2}} \cdot \frac{1}{E_{oc}^2} + \frac{R_z}{\pi R_{dome\_vidente}} \cdot \frac{1}{E_{os}} + \frac{R_z}{E_p} + \frac{R_z}{\frac{\pi R_{cot}^2}{2}} \cdot \frac{1}{E_{cot}} + \frac{R_z}{\frac{\pi R_{tib}^2}{2}} \cdot \frac{1}{E_{p2}}$$

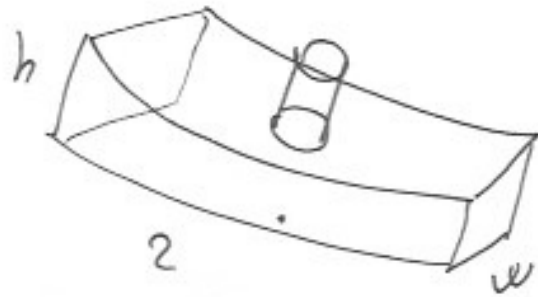
$$\frac{R_z}{\frac{\pi(R_{tib}^2 - R_{st}^2)}{2}} \cdot \frac{1}{E_{oc}^2} + \frac{R_z}{\pi R_{ep2}^2} \cdot \frac{1}{E_{os2}}$$

$$\epsilon_{xy} = \frac{R'_{xv}}{\frac{2}{3} \pi R^3 \epsilon_{p1}} \cdot \frac{1}{E_{osr}} + \frac{R'_{xy}}{\pi R f_{em} h f_{em}} \cdot \frac{1}{E_{ocr}} + \frac{R'_{xy}}{S_{p_{dent}} \cdot w_{dent} + 2\pi r_p h p} \quad (5)$$

$$\cdot \frac{1}{E_{p1}} + \frac{R'_{xv}}{S_{p_{cot}} \cdot \pi r_{cot}} \cdot \frac{1}{E_{cot}} + \frac{R'_{xy}}{\pi R_{st} s_{p f} + \pi r_{st} h_{st}} \cdot \frac{1}{E_{p2}} +$$

$$\frac{R'_{xv}}{\pi r_{tib} \cdot h_{tib}} \cdot \frac{1}{E_{ca}^{xv}} + \frac{R'_{xy}}{\frac{1}{3} \pi R^3 \epsilon_{p2}} \cdot \frac{1}{E_{osr}}$$

$$(1) \frac{R'_z}{\pi R_{dent} \cdot w_{dent}} =$$



$$\frac{R'_{xv}}{S_{p_{dent}} \cdot w_{dent} + 2\pi r_p h p}$$

$$(2) \frac{R'_z}{\frac{\pi}{2} R^2 r_{cot}} = \frac{R'_{xv}}{\pi R r_{cot} d_{cot}}$$

$$(3) \frac{R'_z}{\frac{\pi}{2} R^2 r_{tib}} = \frac{R'_{xv}}{\pi R r_{tib} s_{p_{tib}} + \pi R_{st} h_{st}}$$

fem)  $(R_{p_{dent}}, h_{dent}, r_{int}, r_{est})$

tib)  $(r_{p_{tib}}, \delta_{tib}, r_{p_{tib}}, h_{p_{tib}})$

cot)  $(r_{cot}, \delta_{cot}, l_e)$

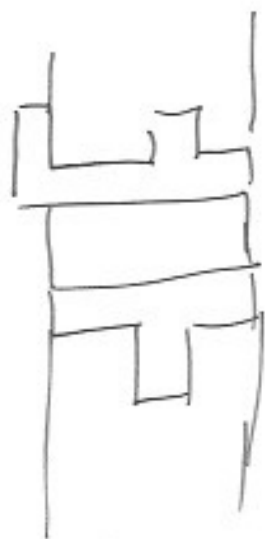
(1)

$r_{cot} = r_{p_{tib}} = r_{est}$

Torsione.

(6)

Tibiale.



$$\sigma_{\text{TORSIONE}}^{\text{fem}} = \frac{R' z}{\pi R_{\text{dento}} w_{\text{dento}}}$$

$$\sigma_{\text{TORSIONE}}^{\text{fem}} = \frac{M_T \cdot z_{\text{fem}}}{I} \quad M_T = R_{xy} \cdot z_{\text{fem}}$$

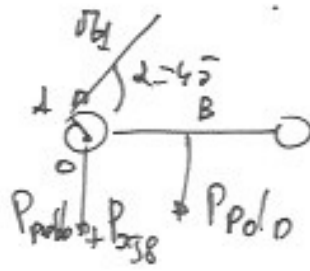
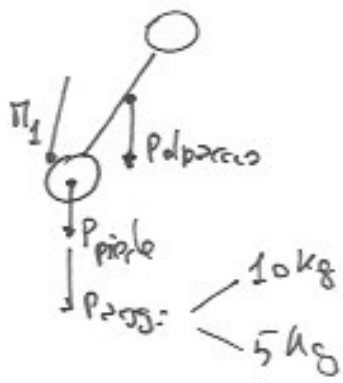


$$I = \frac{\pi}{2} (R_{\text{fem}}^4 - R_{\text{dento}}^4)$$

$$\sigma_{\text{TORSIONE}}^{\text{TIBIALE}} = \frac{R' z}{\frac{\pi}{2} R_{\text{TIBIALE}}^2}$$

$$\sigma_{\text{TORSIONE}}^{\text{tib}} = \frac{M_T \cdot z_{\text{TIBIALE}}}{I} \quad M_T = R_{xy} \cdot z_{\text{tib}}$$

$$I = \frac{\pi}{2} (R_{\text{tib}}^4 - R_{\text{perno}}^4)$$



$$M_1 \cdot \sin \alpha = P_{p10b} \cdot \frac{l_p}{2}$$

$$M_2 = P_{p10b} \cdot \frac{l_p}{2 \cos \alpha}$$

$$\begin{cases} R_z = -P_{p10b} - P_{p25g} - P_{p10} - M_1 \sin \alpha \\ R_{xy} = -M_2 \cos \alpha \end{cases}$$