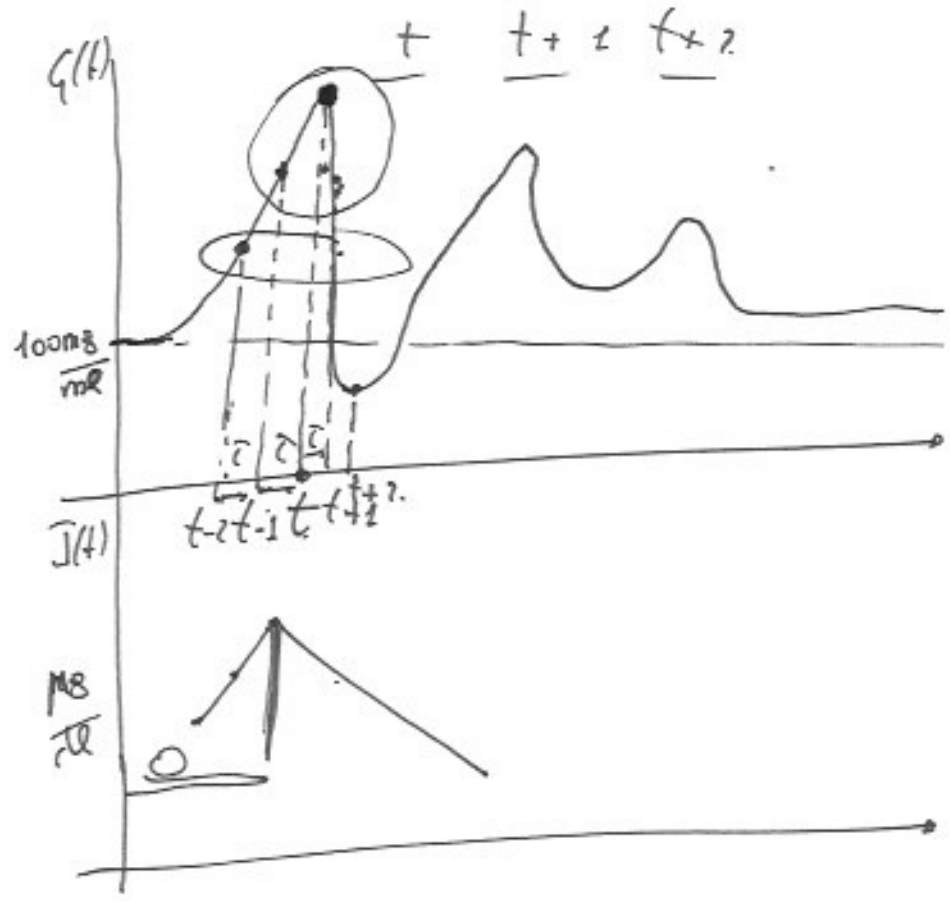


Fisher

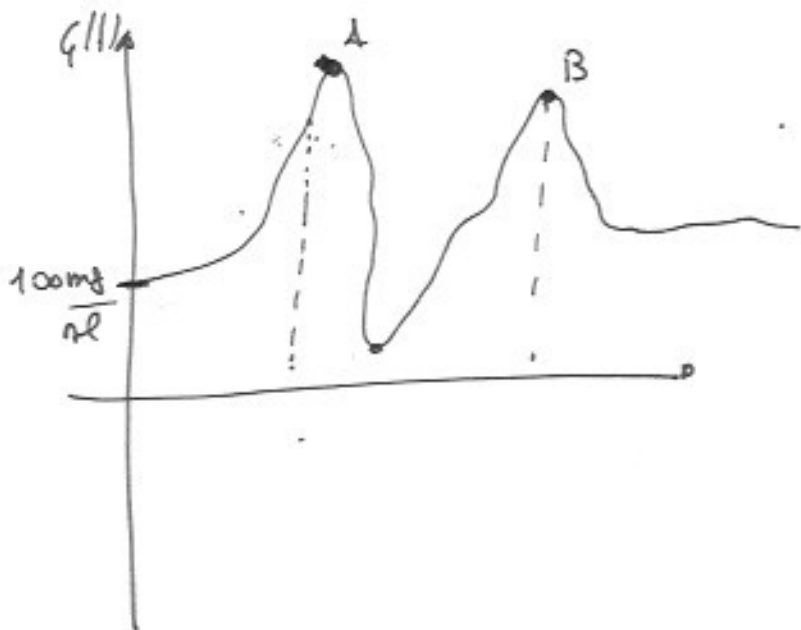


Fisher  $I(t) = \underline{a}_0 + \underline{a}_1 (G(t) - BI) + \underline{a}_2 \frac{dG}{dt}$

$$\begin{cases} I(t) = \underline{a}_0 + \underline{a}_1 (G(t) - BI) + \underline{a}_2 \frac{G(t) - G(t-1)}{\tau} \\ I(t-1) = \underline{a}_0 + \underline{a}_1 (G(t-1) - BI) + \underline{a}_2 \frac{G(t-1) - G(t-2)}{\tau} \\ I(t-2) = \underline{a}_0 + \underline{a}_1 (G(t-2) - BI) + \underline{a}_2 \frac{G(t-2) - G(t-3)}{\tau} \end{cases}$$

$I(t) = I_{max}$   $\tau = 15 \text{ min}$   
 $I(t-1) = I_{max} - \frac{1}{4} I_{max} = \frac{3}{4} I_{max}$   
 $I(t-2) = I_{max} - \frac{1}{4} I_{max} - \frac{1}{4} I_{max} = 0.5 I_{max}$

$\underline{a}_0, \underline{a}_1, \underline{a}_2 > \phi$



$$\underline{I_R} = \textcircled{K} \frac{dG(t)}{dt} \quad \text{dynamics}$$

$$I_n(t) = RI \left[ 1 + \frac{G(t) - BI}{QJ} \right] \quad \text{? statica.} \quad K > 0$$

$$K > \phi$$

$$100 \frac{\mu\text{g}}{\text{dl}} = \textcircled{K_1} \frac{G_A(t) - G_A^{n.w.}(t-1)}{\tau} \quad K_1 = 1$$

$$100 \frac{\mu\text{g}}{\text{dl}} = \textcircled{K_2} \frac{G_B(t) - G_B^{n.w.}(t-1)}{\tau} \quad K_2 = 1$$

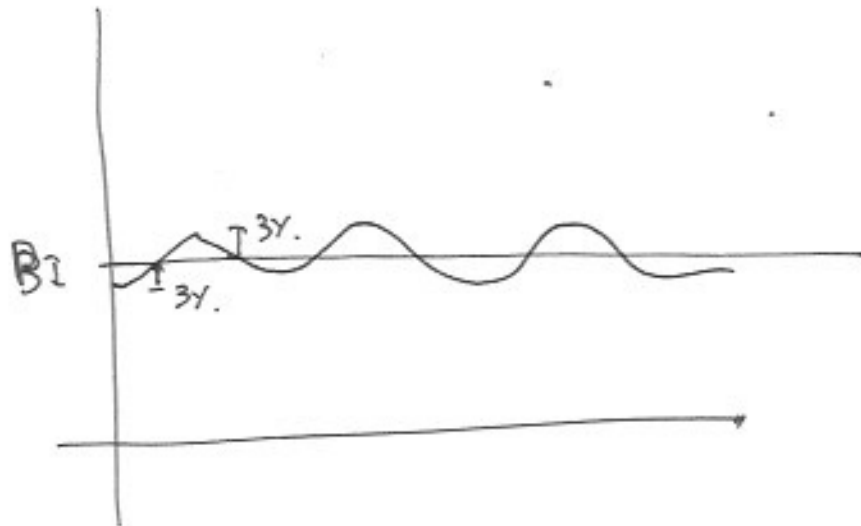
$$\underline{\tau = t_{\text{max}} - t_{\text{min}}}$$

$$\boxed{0 \leq K \leq 1}$$

$K = \max(K_1, K_2) \rightarrow$  gli darei insulina meno

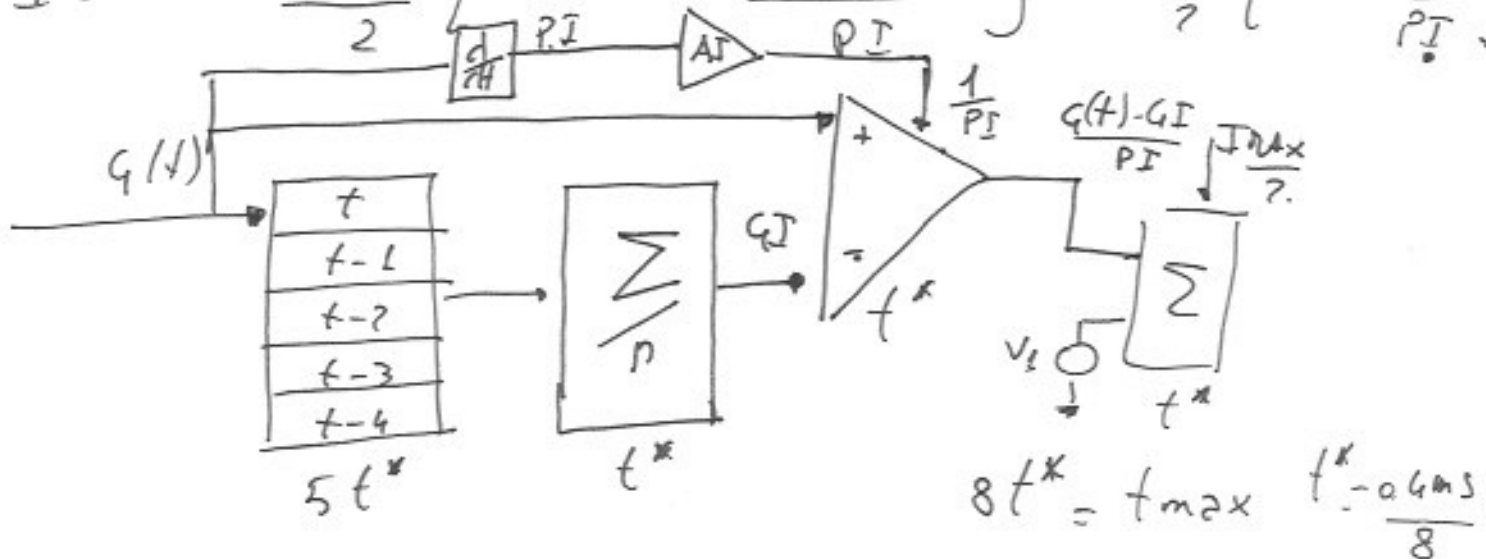
$K = \min(K_1, K_2) \rightarrow$  gli darei  $I_n \geq \phi$

$$\boxed{K = \text{media}(K_1, K_2)}$$



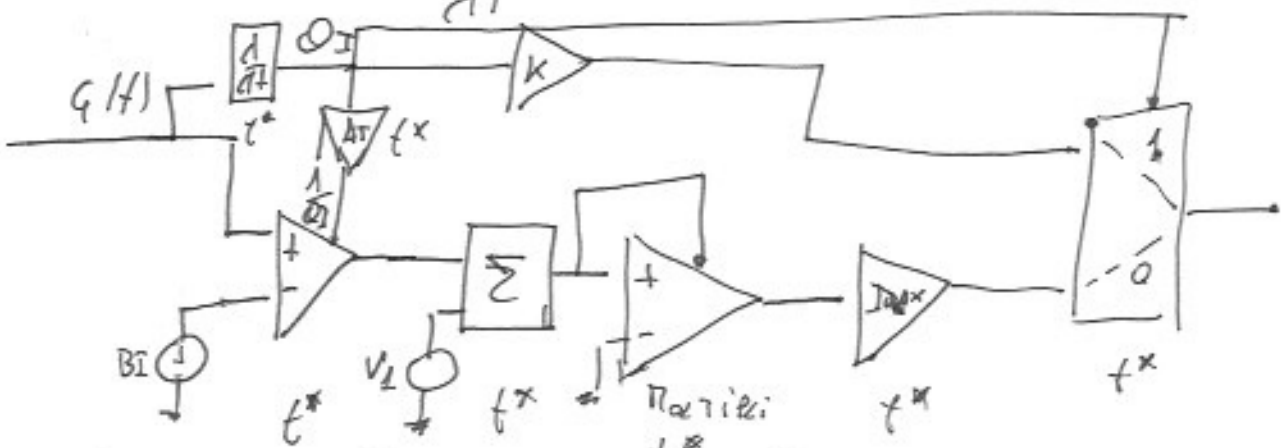
Albi ssp

$$I(t) = \frac{I_{max}}{2} \left[ 1 + \frac{1}{PI} \int_{t^*}^{t^*+PI} G(t) dt \right] \approx \frac{I_{max}}{2} \left[ 1 + \frac{G(t) - G_I}{PI} \right]$$



(lomens  $I_R = I_{max} \left[ 1 + \frac{G(t) - BI}{PI} \right] ?$

$$I_R = K \frac{dG(t)}{dt}$$



$t_{max} = 7t^* \quad t^* = \frac{0.6ms}{7}$

(4)

$$I(t) = 0_0 + 0_1 (G(t) - BT) + a_2 \frac{dG}{dt} \quad \boxed{\text{Fisher}}$$

